



University of  
**Salford**  
MANCHESTER

# Two bioinspired mobile manipulators with rolling locomotion

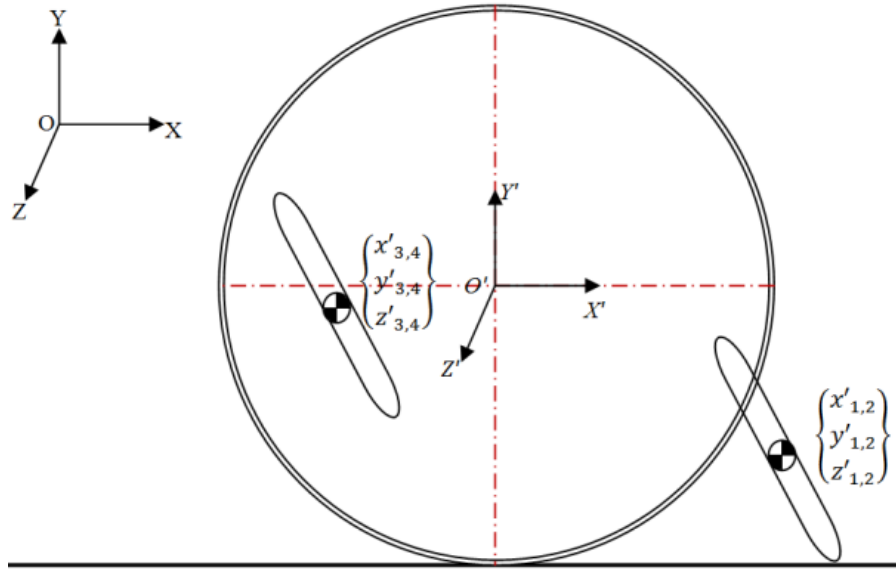
Mahboubi, S, Fakhrabadi, MMS, Davis, ST and Nefti-Meziani, S

[http://dx.doi.org/10.1016/S1672-6529\(14\)60159-1](http://dx.doi.org/10.1016/S1672-6529(14)60159-1)

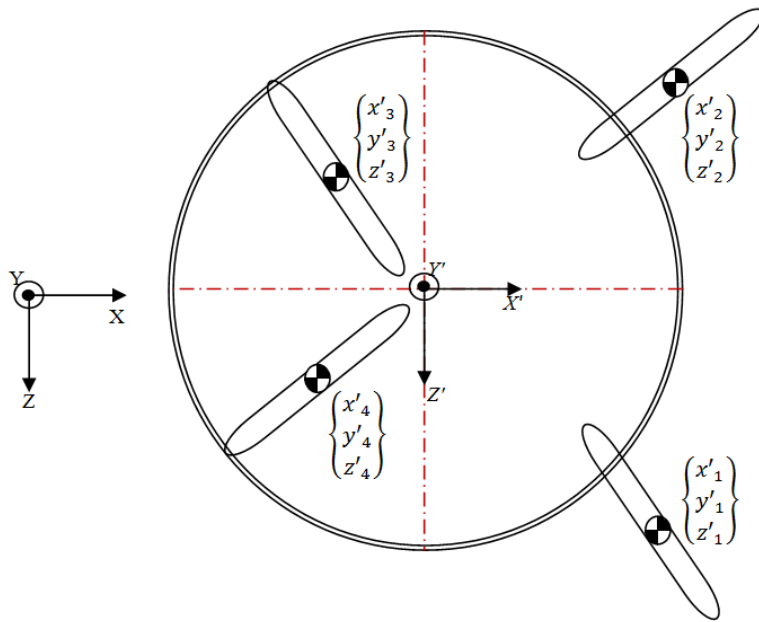
<b>Title</b>	Two bioinspired mobile manipulators with rolling locomotion
<b>Authors</b>	Mahboubi, S, Fakhrabadi, MMS, Davis, ST and Nefti-Meziani, S
<b>Type</b>	Article
<b>URL</b>	This version is available at: <a href="http://usir.salford.ac.uk/id/eprint/37778/">http://usir.salford.ac.uk/id/eprint/37778/</a>
<b>Published Date</b>	2016

USIR is a digital collection of the research output of the University of Salford. Where copyright permits, full text material held in the repository is made freely available online and can be read, downloaded and copied for non-commercial private study or research purposes. Please check the manuscript for any further copyright restrictions.

For more information, including our policy and submission procedure, please contact the Repository Team at: [usir@salford.ac.uk](mailto:usir@salford.ac.uk).



(a)



(b)

Fig. 9