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Two bioinspired mobile manipulators with rolling locomotion

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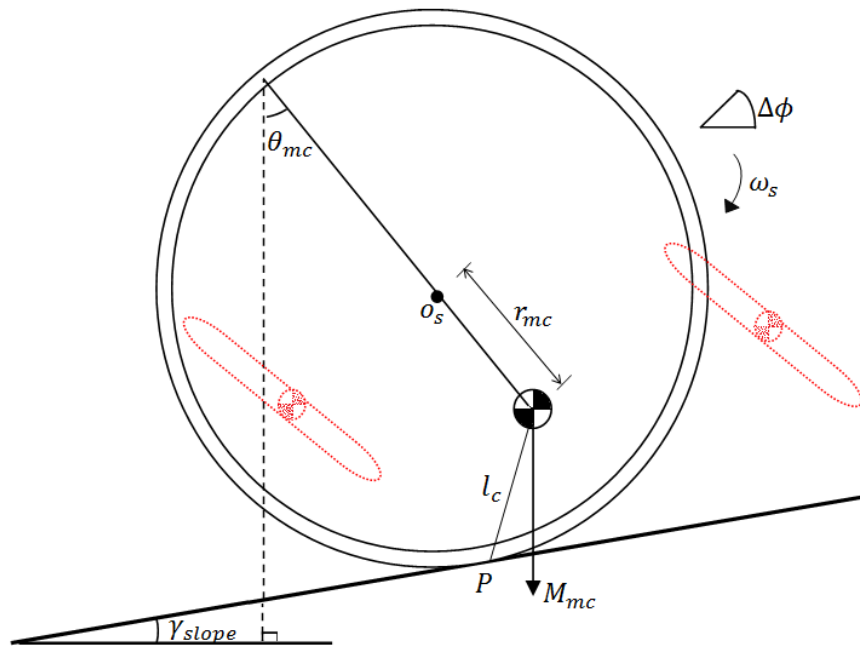


Fig. 10