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Two bioinspired mobile manipulators with rolling locomotion

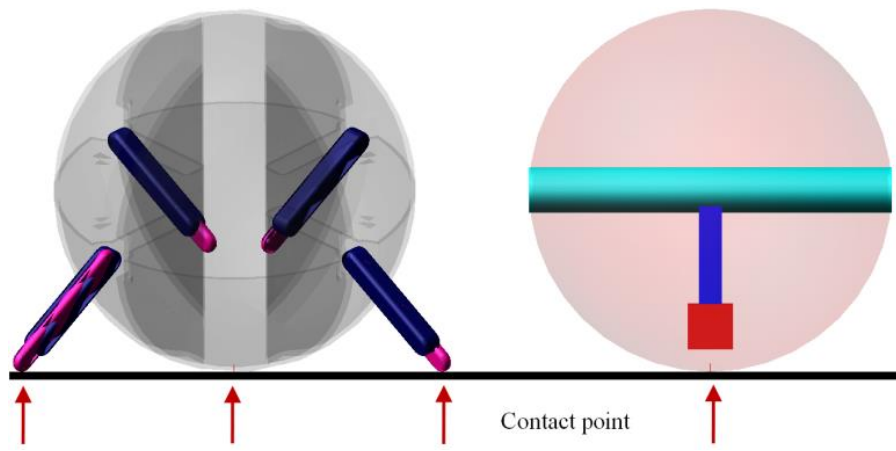
Mahboubi, S, Fakhrabadi, MMS, Davis, ST and Nefti-Meziani, S

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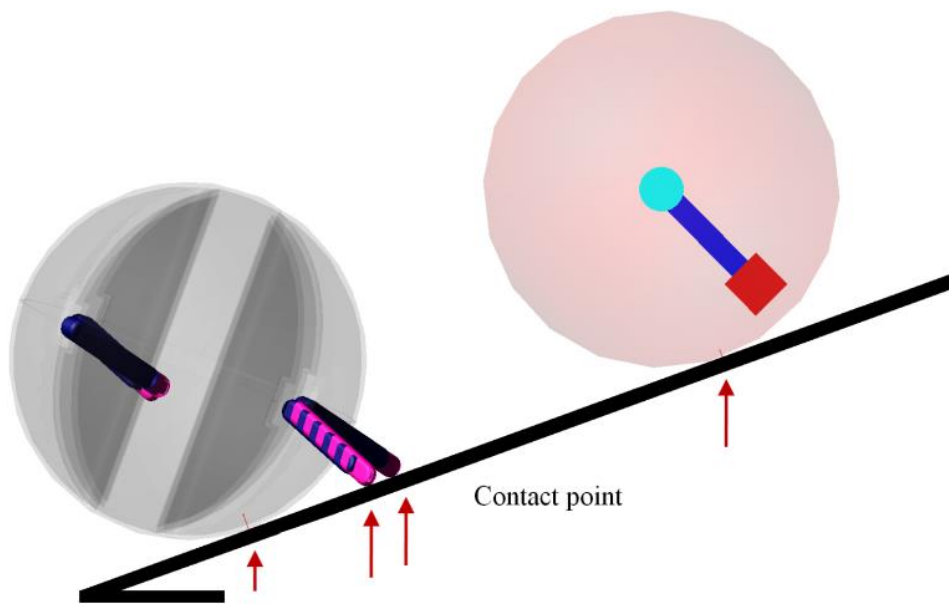
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(a)



(b)

Fig. 11