



University of
Salford
MANCHESTER

Two bioinspired mobile manipulators with rolling locomotion

Mahboubi, S, Fakhrabadi, MMS, Davis, ST and Nefti-Meziani, S

[http://dx.doi.org/10.1016/S1672-6529\(14\)60159-1](http://dx.doi.org/10.1016/S1672-6529(14)60159-1)

Title	Two bioinspired mobile manipulators with rolling locomotion
Authors	Mahboubi, S, Fakhrabadi, MMS, Davis, ST and Nefti-Meziani, S
Type	Article
URL	This version is available at: http://usir.salford.ac.uk/id/eprint/37778/
Published Date	2016

USIR is a digital collection of the research output of the University of Salford. Where copyright permits, full text material held in the repository is made freely available online and can be read, downloaded and copied for non-commercial private study or research purposes. Please check the manuscript for any further copyright restrictions.

For more information, including our policy and submission procedure, please contact the Repository Team at: usir@salford.ac.uk.



(a)



(b)

Fig. 1