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# Validity and reliability of 3D marker based scapular motion analysis : a systematic review

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Validity and reliability of 3D marker based scapular motion analysis: A systematic review

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1 **Validity and reliability of 3D marker based scapular motion analysis: A systematic**  
2 **review**

3  
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22 **Abstract**

23 Methods based on cutaneous markers are the most popular for the recording of three dimensional  
24 scapular motion analysis. Numerous methods have been evaluated, each showing different levels of  
25 accuracy and reliability. The aim of this review was to report the metrological properties of 3D  
26 scapular kinematic measurements using cutaneous markers and to make recommendations based on  
27 metrological evidence.

28 A database search was conducted using relevant keywords and inclusion/exclusion criteria in 5  
29 databases. 19 articles were included and assessed using a quality score. Concurrent validity and  
30 reliability were analyzed for each method.

31 Six different methods are reported in the literature, each based on different marker locations and post  
32 collection computations. The acromion marker cluster (AMC) method coupled with a calibration of  
33 the scapula with the arm at rest is the most studied method. Below 90-100° of humeral elevation, this  
34 method is accurate to about 5° during arm flexion and 7° during arm abduction compared to palpation  
35 (average of the 3 scapular rotation errors). Good to excellent within-session reliability and moderate to  
36 excellent between-session reliability have been reported. The AMC method can be improved using  
37 different or multiple calibrations. Other methods using different marker locations or more markers on  
38 the scapula blade have been described but are less accurate than AMC methods.

1 Based on current metrological evidence we would recommend (1) the use of an AMC located at the  
2 junction of the scapular spine and the acromion, (2) the use of a single calibration at rest if the task  
3 does not reach 90° of humeral elevation, (3) the use of a second calibration (at 90° or 120° of humeral  
4 elevation), or multiple calibrations above 90° of humeral elevation.

## 5 6 **Keywords**

7 Shoulder, accuracy, reliability, validity, scapular kinematics

## 8 **1. Introduction**

9 The measurement of shoulder kinematics during movement provides relevant information for the  
10 diagnosis and treatment of clinical disorders (Fayad et al., 2008b), rehabilitation techniques (Hanratty  
11 et al., 2012), sports performance (Meyer et al., 2008) and injury prevention (Shaheen et al., 2013).

12 Calculation of shoulder joint kinematics using 3D upper-limb motion analysis is usually carried out  
13 with the shoulder considered as a virtual thoraco-humeral joint. The scapulo-thoracic (ST) and gleno-  
14 humeral (GH) joints are not considered individually despite the fact that scapular motion is a vital  
15 component of shoulder function. Indeed, during arm elevation in healthy subjects, there is significant  
16 motion of the scapula relative to the thorax with a mean 2° decrease in protraction, 39° increase in  
17 upward rotation and 21° increase in posterior tilt (Ludewig et al., 2009). Moreover abnormal 3D  
18 shoulder kinematic patterns have been found in frozen shoulder (Fayad et al., 2008a), hemiplegia  
19 (Meskers et al., 2005), impingement syndrome (McClure et al., 2006), children with cerebral palsy  
20 (Brochard et al., 2012) and obstetrical plexus palsy (Duff et al., 2007). This highlights the importance  
21 of 3D dynamic analysis to improve understanding of shoulder movement both in the biomechanical  
22 field and the clinical environment. Tracking of ST motion allows GH motion to be computed, which  
23 provides even more complete information on the dysfunction of the whole shoulder girdle.

24 The main obstacle to performing such a detailed analysis is the difficulty in finding a valid and reliable  
25 method to record scapular motion. Among the various techniques available (radiography, magnetic  
26 resonance imaging, fluoroscopy, inertial sensor, goniometer, etc.) for the measurement of in vivo  
27 scapular kinematics, cutaneous marker based methods (electromagnetic (Johnson et al., 1993; van der

1 Helm and Pronk, 1995; Barnett et al., 1999; Meskers et al., 1999; Karduna et al., 2001; McClure et al.,  
2 2001; Borstad and Ludewig, 2002; Ebaugh et al., 2005; Ludewig et al., 2009) and optoelectronic  
3 methods (Bourne et al., 2007; Lovern et al., 2009; van Andel et al., 2009; Lempereur et al., 2010; Senk  
4 and Cheze, 2010; Brochard et al., 2011b; Jaspers et al., 2011a; Shaheen et al., 2011; Lempereur et al.,  
5 2012) systems) have been the most studied and are the most used techniques for the measurement of  
6 scapular motion in the laboratory setting. However, marker based techniques are subject to  
7 inaccuracies relating to the placement of markers or soft tissue artefacts (STA) (Leardini et al., 2005).  
8 This is particularly true for the tracking of scapular motion: a difference of 87 mm has been found  
9 between the position of markers along the medial border of the scapula and the actual position of the  
10 scapula with the shoulder in full elevation (Matsui et al., 2006). This may question the validity and  
11 reliability of the use of marker based techniques for the recording of scapula motion. In order to  
12 standardize the analysis of shoulder kinematics, the International Society of Biomechanics (ISB) has  
13 published recommendations for the definition of joint coordinate systems and rotation sequences for  
14 the upper limb including the scapula (Wu et al., 2005). Recently, many methods have been described  
15 for the estimation of scapular motion such as the acromial method (a sensor is attached directly over  
16 the acromion and bony landmarks are digitalized to transform coordinates from the acromial sensor to  
17 the scapula coordinate system) (Karduna et al., 2001; van Andel et al., 2009; Brochard et al., 2011b),  
18 or the surface mapping approach (estimation of scapular motion using a cluster of markers over the  
19 scapula) (Jacq et al., 2008; Mattson et al., 2012). The placement of the sensor over the flat part of the  
20 acromion (Shaheen et al., 2011) and the cluster of markers covering the scapula (300 in the study by  
21 Mattson et al. (2012) and 120 in the study of Schwartz et al. (2013)) differ according to the methods.  
22 The method of computation of scapular motion also varies, such as the Calibrated Anatomical System  
23 Technique (CAST) (van Andel et al., 2009), and the double (Brochard et al., 2011a) or multiple  
24 (Prinold et al., 2011) calibrations. More complex algorithms can be used to compute scapular motion  
25 from marker maps such as the IMCP algorithm (Jacq et al., 2008) which is a robust, simultaneous and  
26 multi-object extension of the classic algorithm of registration, Iterative Closest Point (ICP). Moreover,  
27 the local coordinate system used affects the scapular rotations obtained. Significant differences  
28 between the original coordinate system (TrigonumSpinae (TS), acromioclavicular (AC) joint and

1 Angulus Inferior (AI)) and the system currently used (AngulusAcromialis (AA) instead of AC) have  
2 been found (Ludewig et al., 2010). The current standard interprets the same scapular motion with less  
3 internal rotation and upward rotation and more posterior tilt than the original.

4 Despite existing literature on scapular kinematic measurements, a systematic review, pooling existing  
5 knowledge in order that a general consensus can be reached, is lacking in literature.

6 Therefore, the aim of this review was to report the existing marker based methods used to estimate 3D  
7 scapular movements and their metrological properties (concurrent validity and reliability). Based on  
8 this review, recommendations for ST motion analysis tracking and future research are formulated.

## 9 **2. Method**

10 A systematic search of the following electronic databases was performed: Pubmed, Web of Science,  
11 Cochrane Library, Academic Search Premier and Psych Info. Keywords for the search included (1)  
12 Scapula, (2) keywords relative to the concept of accuracy: “accuracy”, “validity”, “agreement”, (3)  
13 keywords relative to reliability: “reliability”, “repeatability”, “reproducibility”. Only full papers  
14 (original articles, short communications or technical notes) published between 1990 and December  
15 2012 were retained. In this paper, validity refers to the general concept of the validity of a measure  
16 (including content validity, concurrent/criterion validity and reliability), accuracy refers to the  
17 concurrent/criterion validity and reliability refers to the within/between rater/session reliability.

18 The titles and abstracts of articles retrieved from the search were assessed independently by two  
19 reviewers (ML and FL). Consensus for inclusion and exclusion was reached by discussion in the case  
20 of disagreement. Papers were included if they satisfied the following criteria: (1) the study included  
21 human participants, (2) the study evaluated a marker based method for the estimation of 3D scapular  
22 motion, (3) concurrent validity and/or reliability were evaluated, (4) full scientific papers. Papers were  
23 excluded if they were not published in English or were cadaver studies. The references in the selected  
24 articles were screened to complete the review process.

25 All studies included were assessed by two reviewers for their methodological quality. Since no  
26 validated quality assessment tool exists for the evaluation of articles in this field, a customized quality  
27 assessment tool was developed and based upon the STROBE statement (STrengthening the Reporting

1 of OBservational studies in Epidemiology) (Vandenbroucke et al., 2007) and a systematic review in  
2 biomechanics (Peters et al., 2010). Table 1 presents the different items. Each item was rated as zero  
3 (no description), one (limited description) and two (good description).

### 4 **3. Results**

#### 5 *3.1. Selection of articles*

6 The electronic database search identified a total of 335 papers. 15 articles were included for the title  
7 and abstract screening. Screening of references identified another 4 papers. Details of the reviewed  
8 articles are summarized in tables 2, 3, 4 and 5.

#### 9 *3.2. Quality of reviewed articles*

10 The quality of the reviewed articles is summarized in table 6.

11 Six of the reviewed studies had a quality assessment score above 80% (Hebert et al., 2000; van Aniel  
12 et al., 2009; Bourne et al., 2011; Brochard et al., 2011a; Lempereur et al., 2012; Warner et al., 2012).

13 Five studies had a quality score between 70% and 80% (Meskers et al., 2007; Bourne et al., 2009;  
14 Lempereur et al., 2010; Senk and Cheze, 2010; Chu et al., 2012) and 8 between 60% and 70%  
15 (Karduna et al., 2001; Lovern et al., 2009; Brochard et al., 2011b; Prinold et al., 2011; Shaheen et al.,  
16 2011; Mattson et al., 2012).

17 Most of the articles were of high quality regarding research objectives, the experimental protocol  
18 (subject number, motion analysis system, position of markers, movements, definition of a reference  
19 method, computation of accuracy), results of concurrent validity, interpretation of the results and the  
20 conclusions. Many articles had limited subject characteristic descriptions, evaluation of reliability and  
21 results. Limitations of the studies were not always discussed. No study performed sample size  
22 calculations.

#### 23 *3.3. Population*

24 Most of the studies assessed the accuracy of 3D scapular motion in healthy young adult subjects.  
25 Lempereur et al. (2012) and Jaspers et al. (2011b; 2011a) also included children with hemiplegic  
26 cerebral palsy. Karduna et al. (2001) included one subject with subacromial impingement syndrome.

### 1 3.4. Motion analysis system

2 The first studies of accuracy used electromagnetic systems which make direct measurements of the  
3 orientations and positions of the sensor in 3D space (Karduna et al., 2001; Meskers et al., 2007).  
4 Among the selected papers, optoelectronic systems have been the most used systems for the estimation  
5 of scapular motion (table 3).

### 6 3.5. Concurrent validity and reliability

#### 7 3.5.1. Marker placements other than on the acromion

8 Three studies put the markers on the anatomical landmarks of the scapula recommended by the ISB  
9 (AA, AI and TS) (Lovern et al., 2009; Lempereur et al., 2010; Brochard et al., 2011b). Bourne et al.  
10 (2009) used 6 surface marker configurations on the scapula whereas Mattson et al. (2012) fixed 300  
11 markers on the scapula. Lempereur et al. (2010) showed that the use of markers on the scapula  
12 produced an error (in comparison with palpation) of up to 15° with increasing humeral elevation  
13 Lovern et al. (2009) found an under-estimation of 50° of upward rotation at full arm elevation.  
14 However, in both of these studies, a correlation between the skin marker method and palpation  
15 (reference method) was performed. Lovern et al. (2009) found a correlation above 0.7 between the 2  
16 approaches, suggesting that it may be possible to predict scapula-thoracic upward rotation using skin-  
17 mounted scapula markers. The model of rotation correction determined by Lempereur et al. (2010)  
18 improved the accuracy to less than 4°. However, the proposed models are not valid for all upper limb  
19 movements but only for the directions of movement measured in these studies. In the study by Bourne  
20 et al. (2011), two surface marker configurations (the six most superior markers and all eight markers  
21 of the model) gave the most accurate scapular motion. However, they indicated that the scapular joint  
22 angles required correction using a skin correction factor due to the low accuracy of skin markers  
23 (Bourne et al., 2009).

24 Two studies assessed the within-session reliability (Lempereur et al., 2010; Brochard et al., 2011b). In  
25 both cases, the reliability was excellent (ICC between 0.88 and 0.98 in Lempereur et al. (2010) and  
26 ICC between 0.90 and 0.94 in Brochard et al. (2011b)). In the study by Bourne et al. (2011), the  
27 between session reliability ranged from 2.6° to 9.1° (RMS differences) showing a good agreement  
28 between the 2 sessions.



### 3.5.2. Acromion Marker Cluster and single calibration

An alternative method is to position a cluster of markers or an electromagnetic sensor on the flat upper surface of the acromion as first described by Karduna et al. (2001). Table 4 presents the different results of the studies which used an acromion marker cluster. The CAST, with a single calibration and a cluster of markers or an electromagnetic sensor on the acromion, was the most used method to estimate scapular rotations. During upper limb flexion, this method was accurate to  $5^{\circ}$  (averaged across rotations) except for the studies by Brochard et al. (2011b; 2011a) and Karduna et al. (2001). During upper limb abduction, the accuracy was slightly lower but was above  $7^{\circ}$ . During elevation in the scapular plane, the method was accurate to  $6^{\circ}$ , whatever the axis of rotation measured. Despite a low average error in both flexion and abduction, many studies found that accuracy was reduced when the AMC method was used above  $90^{\circ}$  of arm elevation (Meskers et al., 2007; van Andel et al., 2009; Brochard et al., 2011b; Brochard et al., 2011a; Shaheen et al., 2011). This is a strong limitation when analyzing large amplitude shoulder movements. Above  $90^{\circ}$  of humeral elevation, the deltoid muscle contraction may create skin movement, increasing soft tissue artifacts although this link has to be proven. The error is generally greater on the Y-axis (protraction) than the other axes.

The placement of the AMC on the flat part of the acromion also influences accuracy. Shaheen et al. (2011) showed that Position C (Position A: near the anterior edge, Position B: just above the acromial angle and Position C: the meeting point between the acromion and scapula spine) was the least affected by soft-tissue deformation and therefore the best position for attaching the AMC.

The within-session reliability of the AMC method has been more studied than the between-session reliability. A good to excellent within-session reliability has been reported (ICC  $> 0.90$  in Brochard et al. (2011b; 2011a), ICC  $> 0.80$  in Jaspers et al. (2011b; 2011a) and inter-trial mean error  $< 5.5^{\circ}$  in Shaheen et al. (2011) and inter-trial variability  $< 2.33^{\circ}$  in Meskers et al. (2007)). The good level of within-session reliability of ST measurement found in Lempereur et al. (2012) for large ranges of shoulder motion and those found by Jaspers et al. (2011b; 2011a) for within and between-session ST kinematics provides evidence that the level of reliability of the use of an AMC in children with hemiplegic cerebral palsy and in typically developing children is good. However, the between session

1 reliability was moderate to excellent (ICC between 0.56 to 0.92) when using the AMC in Brochard et  
2 al. (2011a).

### 3 3.5.3. Acromion Marker Cluster and multiple calibrations

4 The estimation of scapular rotations using the AMC and multiple calibrations was evaluated in 2  
5 studies (Brochard et al., 2011a; Prinold et al., 2011). The error between the proposed methods and  
6 palpation was estimated between 6.00° and 9.19° with a single calibration versus 2.96° to 4.48° with a  
7 double calibration (Brochard et al., 2011a), and between 4° and 7.9° with single calibration versus 1.9°  
8 to 2.5° with four calibrations (Prinold et al., 2011). Bourne et al. (2009) also improved the accuracy of  
9 scapular tracking using several digitizations of scapula landmarks (Bourne et al., 2011). However, no  
10 marker configurations were able to accurately estimate the 3 scapular rotations simultaneously.

11 The between-session reliability of multiple calibrations has been studied only once. It was slightly  
12 lower (ICC ranged from 0.49 to 0.78) than for the single calibration, probably because of the two  
13 measurements of scapular postures for the double calibration (Brochard et al., 2011a).

### 14 3.5.4. Scapula Tracker

15 A scapula tracker consists of a base, which is attached to the mid-portion of the scapula spine, and an  
16 adjustable arm that positions a footpad onto the meeting point between the acromion process and the  
17 scapula spine. Two studies (Karduna et al., 2001; Prinold et al., 2011) used a scapula tracker. They  
18 found that it gave an accurate estimation of scapular rotations, particularly in the study by Prinold et  
19 al. (2011) (accurate to 3° with a single calibration and to 2° with multiple-calibrations during elevation  
20 in the scapular plane). Significant differences were found between the scapula tracker and an acromion  
21 marker cluster with a better accuracy with the scapula tracker for upper limb elevation above 100°.

22 Neither within-session nor between-session reliability have currently been assessed for the scapula  
23 tracker.

### 24 3.5.5. Synthesis

25 The AMC or the scapula tracker used with a calibration at rest provides an accurate estimation of ST.  
26 Above 90° of thoraco-humeral elevation, the scapula tracker seems to be more accurate, particularly  
27 for protraction (Karduna et al., 2001).

1 Among the different methods, the AMC is the most used method for the estimation of ST and is a  
2 reliable tool to quantify scapular rotations in children and adults (Brochard et al., 2011a; Jaspers et al.,  
3 2011b; Jaspers et al., 2011a).

4 A single calibration with the arm at rest and the use of an AMC gives a good estimation of scapular  
5 rotations with an excellent within-session reliability, as long as thoraco-humeral elevation remains  
6 below 90° during the movement (van Andel et al., 2009; Brochard et al., 2011b; Lempereur et al.,  
7 2012). The association of the AMC with double or multiple calibrations improves accuracy, especially  
8 at high degrees of humeral elevation (Brochard et al., 2011a; Prinold et al., 2011). Reliability ranges  
9 from good to excellent for within session reliability and from moderate to good for between session  
10 reliability (Brochard et al., 2011a).

#### 11 *3.5.6. Method of reference*

12 The scapula locator was the device most often used to estimate the 'real' position of the scapula. It  
13 allows the position of 3 anatomical landmarks (generally AI, AA and TS) to be obtained  
14 simultaneously, in contrast with the palpation method (in which the 3 landmarks are palpated one  
15 after the other) used in 4 studies. The studies by Karduna et al. (2001) and Bourne et al. (2009) used  
16 intra-cortical pins implanted into the scapular spine. More recently, medical imaging such as X-rays  
17 combined with a video-based motion analysis have been used to validate data (Chu et al., 2012).

#### 18 *3.5.7. Tasks*

19 The tasks most used for the estimation of concurrent validity were flexion and abduction of the upper  
20 limb, although some studies assessed elevation in the scapular plane (Prinold et al., 2011; Shaheen et  
21 al., 2011; Chu et al., 2012; Warner et al., 2012) or shoulder internal/external rotation (Karduna et al.,  
22 2001; van Andel et al., 2009; Chu et al., 2012; Mattson et al., 2012). To assess reliability, tasks  
23 relating to activities of daily living such as hand to mouth, hand to neck or forward reaching were also  
24 evaluated (Jaspers et al., 2011b; Jaspers et al., 2011a; Lempereur et al., 2012).

#### 25 *3.5.8. Statistical tools and methodology designs*

26 The Root Mean Square (RMS) error between the tested method and the method of reference was  
27 generally used to quantify errors. In most of the studies, an ANOVA with the independent variables:  
28 measurement method and humeral elevation was then performed to show if there was a significant

1 difference between the method and the reference method. One study used Pearson's correlation  
2 coefficient and RMS to evaluate the accuracy. No studies performed sample size calculations.  
3 The intra-class coefficient was generally used to assess reliability with the standard error of  
4 measurement.

#### 5 **4. Discussion**

6 Advances in motion analysis systems have made the recording of 3D ST joint motion possible, thus  
7 providing a more physiological measurement of shoulder kinematics. This systematic review included  
8 19 studies which evaluated the metrological properties of 6 different marker based methods and  
9 showed the difficulty of setting one method as a reference for everyday clinical and research practice.  
10 The most evaluated method was the AMC with a calibration of the scapula with the arm at rest. Below  
11 90-100° of humeral elevation, this method is accurate to 5° for flexion and 7° for abduction compared  
12 to palpation and depends highly on the position of the AMC on the acromion process (Shaheen et al.,  
13 2011), the number of calibrations and the degree of humeral elevation when calibrating (Prinold et al.,  
14 2011). Other methods using different marker locations or more markers on the scapula blade have  
15 been described but they are less accurate than AMC methods and are more relevant for research than  
16 clinical use.

##### 17 *4.1. Recommendations of the International Society of Biomechanics*

18 To facilitate comparison of results between studies of scapular motion, the International Society of  
19 Biomechanics recommends the use of AA, AI and TS for the definition of the scapular joint  
20 coordinate system and the YXZ Euler sequence for the calculation of joint angles (Wu et al., 2005).  
21 This sequence is consistent with both research- and clinical-based two-dimensional representations of  
22 scapular motion (Karduna et al., 2000). Indeed, Karduna et al. (2000) found that changing the  
23 sequence results in significant alterations in the description of motion, with differences up to 50°. The  
24 use of the proposed scapular landmarks (AA, TS and AI) compared to the original ones (AC, TS and  
25 AI) reduces the risk of gimbal-lock and results in less internal rotation and upward rotation, and more  
26 posterior tilt (Ludewig et al., 2010). The tracking method used is also important when estimating 3D  
27 kinematics. The ISB advises to digitize anatomical landmarks with reference to a technical coordinate

1 system instead of using skin mounted markers during movement. Lempereur et al. (2010) and Lovern  
2 et al. (2009) confirmed that large errors occur when tracking scapular landmarks without a technical  
3 coordinate system especially above 90° of humeral elevation.

#### 4 *4.2. AMC*

5 The association of an AMC and single calibration creates errors of less than 5° for flexion, less than 7°  
6 for abduction and less than 6° for elevation in the scapular plane. The AMC has been shown to create  
7 small errors up to 90° of humeral elevation in many studies and above this threshold the errors are  
8 significantly larger. In specific cases, individual subject differences reach extreme values of  
9 approximately 25° (van Andel et al., 2009). Shaheen et al. (2011) advocated the attachment of the  
10 AMC at the meeting point between the acromion and the scapular spine since this placement created  
11 the smallest errors (below 90° of humeral elevation).

12 No standardized AMC has been developed and therefore, each motion analysis laboratory which  
13 carries out measurements of shoulder and scapular motion has created its own. Moreover, there is no  
14 consensus regarding the design and dimensions, the diameter of the markers or its weight. We  
15 recommend a light AMC with 3 well spaced out markers or electromagnetic receiver, which do not  
16 contact the skin during movements, placed at the meeting point between the acromion and the scapular  
17 spine.

18 For measurements of upper limb elevation above 90°, the AMC yields good results if the calibration is  
19 performed at 90° or 120° (Shaheen et al., 2011). The double or multiple-calibrations reduce errors by  
20 at least 50% in comparison to a single calibration and especially, they improve accuracy at high  
21 degrees of humeral elevation (Brochard et al., 2011a; Prinold et al., 2011). The limitations of these  
22 techniques are the time needed for the calibration and post data processing and the potential errors  
23 generated by multiple palpations. Further studies are needed to reach a compromise between the  
24 number of calibrations and the level of error.

#### 25 *4.3. Validation issues*

26 Studies of concurrent validity were generally performed on healthy young adults and on typically  
27 developing children and children with hemiplegic cerebral palsy. The AMC has not been validated in  
28 pathological populations other than children with cerebral palsy, neither has it been validated in

1 athletes with a large muscle mass. The validation is also generally performed during flexion and  
2 abduction. However, the validation of the AMC during functional movements such as hand to pocket,  
3 hand to head or hand to mouth might generate other results regarding accuracy.

4 The scapula locator is the method generally used to validate the different methods and is considered as  
5 'silver standard' (Cutti and Veeger, 2009). Indeed, de Groot (1997) stated that there is a palpation error  
6 of about  $2^\circ$  which could increase the risk of validity errors.

7 The gold standard remains intra-cortical pins and has been used, for instance, to evaluate typical  
8 scapula-thoracic joint kinematics (Ludewig et al., 2009). Less invasive, the fluoroscopy or dynamic X-  
9 ray, such as that used in the study of Chu et al. (2012), appears to be an alternative method to evaluate  
10 validity. Another limit of the proposed methods is that static positions are compared to dynamic  
11 measurements. Cutti and Veeger (2009) suggest that it is important to compare both the quasi-static  
12 and the dynamic measurements with a gold standard. However, currently the only invasive technical  
13 solution is fluoroscopy which could be a good candidate for a gold standard status.

#### 14 *4.4. Reliability*

15 Only a few studies performed both validations of accuracy and reliability even though these  
16 metrological properties represent different qualities of a measurement (Meskers et al., 2007; van  
17 Andel et al., 2009; Lempereur et al., 2010; Bourne et al., 2011; Brochard et al., 2011b; Brochard et al.,  
18 2011a; Shaheen et al., 2011; Lempereur et al., 2012). Results for reliability show good to excellent  
19 within-session reliability whereas the inter-session errors are higher. These differences might be  
20 related to palpation inaccuracies, differences in marker placement, lack of control of the plane of arm  
21 elevation (Ludewig et al., 2009) or the speed of the movement (Prinold et al., 2013). The knowledge  
22 of measurement error magnitude (whatever the accuracy and/or the reliability) is important in clinical  
23 decision making. Indeed, clinicians must be able to identify significant deviations from the values of  
24 healthy subjects and to differentiate between measurement errors and 'real' changes.

#### 25 *4.5. Limits and recommendations for future research*

26 4 research teams published 10 of the 19 papers included. Since it is known that reliability is very  
27 observer dependent, the good to excellent results found in most of the reliability studies may be lower

1 when using the method for the first time. This may also affect the generalization of the results of this  
2 review.

3 Only 6 papers had quality scores above 80%. Although we highlighted the main results of the high  
4 quality papers we did not exclude low quality papers. One statistical issue which was common to all  
5 studies was the lack of sample size calculation. Recommendations exist for power and a priori sample  
6 size calculation for reliability studies that could be used in ST measurement validation studies  
7 (Eliaszew et al., 1994). Future studies should carry out such calculations in order to produce high  
8 quality studies.

9 Most of the validation studies have been carried out in healthy populations and may not be valid in  
10 pathological or sports populations. Shoulder bone deformities which occur in some pathologies  
11 (arthritis, hemiplegia or obstetrical brachial plexus palsy) or differences in muscle mass may affect the  
12 validity of the tracking method. Further validations should be carried out in the specific populations  
13 that are targeted by these methods.

14 It is also difficult to compare studies due to the different Euler sequences used for thoraco-humeral  
15 elevation (both flexion and abduction), the different levels of maximal humeral elevations and the  
16 standardization or not of humeral elevation between subjects, and the placement of the AMC. For  
17 validity studies, we recommend the use of the ZXY Euler sequence for the calculation of TH during  
18 flexion and the XZY Euler sequence for abduction with a standardization of the humeral elevation  
19 angles across subjects by fitting spline functions through the raw data of consecutive trials.

20 Tracking ST joint kinematics based on cutaneous markers remains a challenge and it is highly  
21 probable that the most accurate method would be a marker-less approach. However, a 3D dynamic  
22 approach has not yet been described. Biplanar fluoroscopy (Zhu et al., 2012) or 3D video cameras  
23 (Jacq et al., 2010) may help to produce more accurate recordings. Other static radiological methods  
24 (low-dose stereoradiographic imaging (EOS) (EOS imaging, France) (Dubousset et al., 2005), open  
25 MRI (Graichen et al., 2000)) might also serve as reference methods to avoid STA or/and to quantify  
26 them. Combining static imaging and motion analysis is also a way to explore shoulder motion (Chu et  
27 al., 2012).

#### 1 4.6. Recommendations for practice

2 Currently, the marker based approach remains the best compromise for measuring shoulder kinematics  
3 based on a two joint model: ST and GH. Based on the results of this review regarding measurement of  
4 ST motion we recommend (1): the use of an AMC located at the junction of the spine of the scapula  
5 and the acromion, (2) use of a single calibration at rest if the task does not reach 90° of humeral  
6 elevation in abduction and flexion, (3) use of a second calibration at 90° or 120° of humeral elevation,  
7 multiple calibrations or a scapula tracker for movements above 90° of thoraco-humeral elevation.  
8 Others methods may have some research applications such as the estimation of STA.

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#### 11 **Conflict of interest**

12 None of the authors have any conflicts of interest in conducting the experiment or in  
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 22

23 **Table 1: Quality analysis form used in systematic review**

Q1	Is there in the abstract an explication of what has been done and found?
Q2	Is the scientific context clearly explained?
Q3	Are the objectives clearly stated?
Q4	Is the sampling size stated?
Q5	If yes, is the sampling size statically justified?
Q6	Are the characteristics of the subjects (height, weight, sex, healthy or pathologic subject) described?
Q7	Is the motion analysis system described?
Q8	Are marker locations including thorax and humerus accurately described?
Q9	Are the movement tasks defined?
Q10	Is the gold standard defined?
Q11	Is the accuracy computation described?
Q12	Is the reliability computation described?
Q13	Are the statistical tools used to show significant differences?
Q14	Are the results about the accuracy described?
Q15	Are the results about reliability described?
Q16	Are the results interpretable?
Q17	Are the limitations of the study discussed?
Q18	Is the conclusion clearly stated?

- 24  
 25 0 (no description), 1 (limited description) and 2 (good description)  
 26  
 27

1 **Table 2: Description of the study population for the selected papers**

Study	Subjects (number)	Mean age (std)	Gender
Chu et al. (2012)	Healthy (5)	27.8 (6.9)	5M
Warner et al. (2012)	Healthy (26)	18-43; 26.1 (6)	11M & 15F
Mattson et al. (2012)	Healthy (12)	NR	2M & 10F
Lempereur et al. (2012)	Healthy (10) // CP (10)	11.2 (3.1) // 11.8 (3.6)	5M & 5F // 5M & 5F
Shaheen et al. (2011)	Healthy (7)	23.9 (3.9)	7M
Prinold et al. (2011)	Healthy (10)	27 (4)	10M
Brochard et al. (2011a)	Healthy (12)	18-41; 26 (6.18)	NR
Brochard et al. (2011b)	Healthy (12)	18-35; 26.1 (NR)	NR
Bourne et al. (2011)	Healthy (8)	30 (5)	5M & 3F
Jaspers et al. (2011a)	Healthy (10)	10.3 (3.2)	6M & 4F
Jaspers et al. (2011b)	CP (12)	10.2 (3.2)	6M & 6F
Senk & Chèze (2010)	Healthy (5)	31 (NR)	4M & 1F
van Andel et al. (2009)	Healthy (13)	22-33	6M & 7F
Lovern et al. (2009)	Healthy (10)	27.5 (5.1)	6M & 4F
Bourne et al. (2009)	Healthy (8)	NR	NR
Bourne et al. (2009)	Healthy (8)	30 (5)	5M & 3F
Meskers et al. (2007)	Healthy (8)	29 (10)	4M & 4F
Karduna et al. (2001)	Healthy (8) // Impingement (1)	33 (NR) // 25	5M & 3F // 1M
Hébert et al. (2000)	Healthy (1) // anatomical model of scapula	46	1M

2

3 M: Male

4 F: Female

5 CP: Cerebral Palsy

6 NR: Not Reported

7

1 **Table 3: Task and measurement methods for the selected papers**

Study	Motion capture system	Study about	Method of reference	Method	Task	Amplitude	Standardization of humeral elevation between subjects	Humerothoracic elevation
Chu et al. (2012)	Opto-electronics - Vicon	Accuracy	DSX	AMC with single calibration	Abd	30–150	NR	Yes
					EleScaPlane	30–150	NR	Yes
					Int/Ext Rot	40–35	NR	Yes
Warner et al. (2012)	Opto-electronics - Vicon	Accuracy	Scapula Locator	AMC with single calibration	Flex	0–120	NR	Yes
					Abd	0–120	NR	Yes
					EleScaPlane	0–120	NR	Yes
Mattson et al. (2012)	Opto-electronics - Motion Analysis	Accuracy	Palpation (AA, (TS+AA)/2, TS, (TS+AI)/2, AI)	Surface Mapping	Abd	NR	NR	Yes
					HBB	NR	NR	Yes
					Ext Rot	NR	NR	Yes
					Int Rot	NR	NR	Yes
					HtM	NR	NR	Yes
					HtN	NR	NR	Yes
Lempereur et al. (2012)	Opto-electronics - Vicon	Accuracy and reliability	Scapula Locator	AMC with single calibration	Flex	20–120	Yes	Yes
					Abd	20–120	Yes	Yes
Shaheen et al. (2011)	Opto-electronics - NR	Accuracy and reliability	Scapula Locator	AMC with single calibration (5 calibration positions) and 3 positions of AMC	EleScaPlane / Pos A	25–140	NR	Yes
					EleScaPlane / Pos B	25–140	NR	Yes
					EleScaPlane / Pos C	25–140	NR	Yes
Prinold et al. (2011)	Opto-electronics - Vicon	Accuracy	Scapula Locator	AMC / ScaTra with 4 calibration	EleScaPlane	30–120	NR	Yes
Brochar et al. (2011a)	Opto-electronics - Vicon	Accuracy and reliability	Scapula Locator	AMC with single and double calibration	Flex	0–120	Yes	Yes
					Abd	0–120	Yes	Yes
Brochar et al. (2011b)	Opto-electronics - Vicon	Accuracy and reliability	Palpation of AA, AI, TS	Markers on AA, AI, TS; AMC; anatomical AMC	Flex	30–110	Yes	Yes
					Abd	30–110	Yes	Yes
Bourne et al. (2011)	Opto-electronics - Optotrack	Accuracy and reliability	Palpation of AA, AI, TS	Clusters of markers	GH Abd	NR	NR	Yes
					GH Horiz Add	NR	NR	Yes

		ty		on scapula	Forward Reaching HBB	NR	NR	Yes
						NR	NR	Yes
Jaspers et al. (2011a)	Opto-electronics - Vicon	Reliability	--	AMC with single calibration	3 reach tasks 2 reach to grasp tasks 3 gross motor tasks	NR	NR	NR
Jaspers et al. (2011b)	Opto-electronics - Vicon	Reliability	--	AMC with single calibration	3 reach tasks 2 reach to grasp tasks 3 gross motor tasks	NR	NR	NR
Senk & Chèze (2010)	Opto-electronics - Motion Analysis	Accuracy	Palpation of AA, AI, TS	Local optimisation procedure built from AC, AA and (TS+AA) /2 and recalculation of TS and AI	Flex Abd Horizontal Flexion	90–180 90–180 0–90	NR NR NR	NR NR NR
Lempereur et al. (2010)	Opto-electronics - Vicon	Accuracy and reliability	Palpation AA, AI, TS	Markers on AA, AI, TS	Flexion	0–160	NR	NR
van Andel et al. (2009)	Opto-electronics - Optotrack	Accuracy and reliability	Scapula Locator	AMC	Flex Abd Int/Ext Rot	20–100 20–100 60–90	Yes Yes Yes	Yes Yes Yes
Lovern et al. (2009)	Opto-electronics - Qualisys	Accuracy	Scapula Locator	Markers on AA, AI, TS	Flex Abd	NR NR	NR NR	Yes Yes
Bourne et al. (2009)	Opto-electronics - Optotrack	Accuracy	Pins	Clusters of markers on scapula and palpation of AA, AI, TS	GH Abd GH Horiz Add Forward Reaching HBB	NR NR NR NR	NR NR NR NR	Yes Yes Yes Yes
Meskers et al. (2007)	Electromagnetics - Flock of birds	Accuracy and reliability	Scapula Locator	AMC	Flex Abd	30–130 30–130	Yes Yes	Yes Yes
Karduna et al. (2001)	Electromagnetics - Polhemus	Accuracy	Pins	AMC / ScaTra	EleScaPlane Flex Horiz Add Int/Ext	10–150 NR NR NR	NR NR NR NR	Yes Yes Yes Yes



					Rot			
Hébert et al. (2000)	Opto-electronics - Optotrack	Accuracy and reliability	Palpation	Markers on AC, AI, TS	15 imposed displacements	0-35	No	No

1

2 AMC: Acromion Marker Cluster, SCaTra: Scapula Tracker

3 AA: Angulus Acromialis, AI: Angulus Inferior, TS: Trigonum Spinae, AC: Most dorsal point on the  
4 acromioclavicular joint

5 Flex: Flexion, Abd: Abduction, EleScaPlane : Elevation in the Scapular Plane, HBB: Hand Behind

6 Back, Ext Rot: External Rotation, Int Rot: Internal Rotation, HtM: Hand to Mouth, HtN: Hand to

7 Neck, GH Abd: GlenoHumeral Abduction, GH Horiz Add: GlenoHumeral Horizontal Adduction.

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Accepted manuscript

1 **Table 4: Results of the accuracy for the selected papers**

Study	Method of reference	Method	Movement	Accuracy method	Statistical tool	Error			Remark	Amplitude
						Y	X	Z		
Chu et al. (2012)	DSX	AMC with single calibration	Abd EleScaPlane Int/Ext Rot	RMSE		3.7 6.2 5.9	4.6 4.5 14.2	5.3 7.0 6.7		30–150 30–150 40–35
Warner et al. (2012)	Scapula Locator	AMC with single calibration	Flex Abd EleScaPlane	RMSE, mean difference, limits of agreement	ANOV A	3.5 4.4 4.0	4.3 4.8 6.1	4.7 5.9 7.3	RMSE max	0–120 0–120 0–120
Mattson et al. (2012)	Palpation (AA, (TS+AA) /2, TS, (TS+AI) /2, AI	Surface Mapping	Abd HBB Ext Rot Int Rot HtM HtN	RMSE, mean error	ANOV A	3.5 2.3 5.1* 5.3* 5.1* 4.2*	4.6* 3.2* 4.2 3.9 4.2 5.9*	3.5 *5.0 4.7* 4.1 3.2 2.9	p<0.1	NR NR NR NR NR NR
Lempereur et al. (2012)	Scapula Locator	AMC with single calibration	Flex Abd	RMSE	ANOV A	3.40 7.69*	5.23* 4.92	4.47 6.26	p<0.05	20–120 20–120
Shaheen et al. (2011)	Scapula Locator	AMC with 5 calibrations (0°, 30°, 60°, 90° and 120°) and 3 positions of the acromial cluster (Pos A: near the anterior edge, Pos B: just above the acromial angle, Pos C: meeting point between the acromion and scapula spine)	EleScaPlane / Pos A / Calibration 1 to 5 EleScaPlane / Pos B / Calibration 1 to 5 EleScaPlane / Pos C / Calibration 1 to 5	RMSE		Figure Figure Figure	Figure Figure Figure	Figure Figure Figure		25–140 25–140 25–140
Prinold et al. (2011)	Scapula Locator	AMC / ScaTra with 4 calibrations (30°, 60°, 90°, 120°, multi)	EleScaPlane / AMC / 30° EleScaPlane / AMC / 60° EleScaPlane / AMC / 90° EleScaPlane / AMC / 120° EleScaPlane / AMC / multi EleScaPlane / ScaTra / 30° EleScaPlane / ScaTra / 60° EleScaPlane / ScaTra / 90° EleScaPlane / ScaTra / 120°	RMSE		7.8 6.7 5.9 6.1 2.2 3.8 3.4 2.6 3.7	4 3.7 3.2 4.8 1.9 4.8 3 2.8 3.2	7 7 6 5.9 2.5 3.8 3.1 2.5 3		30–120 30–120 30–120 30–120 30–120 30–120 30–120 30–120 30–120

			EleScaPlane / ScaTra / multi			1.8	1.7	1.6		30–120
Brochard et al. (2011a)	Scapula Locator	AMC with single and double calibration	Flex / AMC / single calibration	RMSE	ANOVA	6.87	6.03*	8.92*		0–120
			Abd / AMC / single calibration			6.42*	6.00*	9.19*	0–120	
			Flex / AMC / double calibration			4.48*	3.59	2.96	0–120	
			Abd / AMC / double calibration			3.74	3.24	3.43	0–120	
Brochard et al. (2011b)	Palpation of AA, AI, TS	Markers on AA, AI, TS; AMC; anatomical AMC	Flex / Markers on AA, AI, TS	RMSE	ANOVA	4.94*	6.65*	6.06*		30–110
			Abd / Markers on AA, AI, TS			1.55	7.85*	6.80*		
			Flex / AMC			9.33*	4.47	2.14		
			Abd / AMC			8.87*	3.51	8.79*	30–110	
			Flex / anatomical AMC			11.05*	3.52	2.4		
Bourne et al. (2011)	Palpation of AA, AI, TS	6 clusters of markers on scapula	GH Abd	RMSE	Figure					NR
			GH Horiz						NR	
			Add Forward Reaching						NR	
			HBB						NR	
Senk & Chèze (2010)	Palpation of AA, AI, TS	Local optimisation procedure built from AC, AA and (TS+AA)/2 and recalculation of TS and AI	Flex	RMSE		9.7	8.3	10.3	Mean of RMSE from 90° to 150°	90–180
			Abd			5.4	7.5	7.8	90–180	
			Horizontal Flexion			5.0	7.7	7.6	0–90	
Lempereur et al. (2010)	Palpation AA, AI, TS	Markers on AA, AI, TS	Flexion	Maximal difference	ANOVA	14.86*	14.21*	16.16*		0–160
			Flexion			1.74	3.98	2.75	Correction model	
van Andel et al. (2009)	Scapula Locator	AMC	Flex	Mean difference	ANOVA	Figure ErrorY<6*	Figure ErrorX<3	Figure ErrorZ<5	Mean difference	20–100
			Abd			Figure ErrorY<4	Figure ErrorX<6*	Figure ErrorZ<5		20–100
			Int/Ext Rot			Figure ErrorY<8.4	Figure ErrorX<4	Figure ErrorZ<6		60–90
Lovern et al. (2009)	Scapula Locator	Markers on AA, AI, TS	Flex Abd							NR NR
Bourne et al. (2009)	Pins	Clusters of markers on scapula and palpation of AA, AI, TS	GH Abd	RMSE		9.5	7.5	9.7	Un-corrected angles	NR
			GH Horiz			7	6.4	4.8		NR
			Add Forward Reaching			6	4.2	5.1		NR
			HBB			5.1	7.8	9.7		NR

			GH Abd	RMSE		2.8	2.8	2.4	Correcti on of the joint angles	NR
			GH Horiz			2.3	1.9	1.4		NR
			Add							
			Forward Reaching HBB			2.2	2	3		NR
						1.8	1.6	2.3		NR
Meskers et al. (2007)	Scapula Locator	AMC	Flex	Mean differen ce	ANOV A	Figure 2.5<Error Y<6	Figure - 1<ErrorX <1	Figure - 5<Error Z<-2		30-130
			Abd			Figure 0<ErrorY< 2.5	Figure - 9<ErrorX <-3	Figure - 4<Error< -1		30-130
Karduna et al. (2001)	Pins	AMC / ScaTra	EleScaPlane / AMC	RMSE		9.4	6.3	6.6		10-150
			Flex / AMC			11.4	5.9	8.6		NR
			Horiz Add / AMC			10.0	4.8	7.3		NR
			Int/Ext Rot / AMC			6.2	4.4	3.7		NR
			EleScaPlane / ScaTra			3.2	8.0	4.7		10-150
			Flex / ScaTra			3.8	8.4	6.2		NR
			Horiz Add / ScaTra			5.0	10.0	3.8		NR
			Int/Ext Rot / ScaTra			4.4	7.2	4.6		NR
Hébert et al. (2000)	Palpation	Markers on AC, AI, TS	15 imposed displaceme nts	Mean differen ce		1.73 for all movements imposed on the model				0-35

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AMC: Acromion Marker Cluster, SCAtra: Scapula Tracker  
AA: Angulus Acromialis, AI: Angulus Inferior, TS: Trigonum Spinae, AC: Most dorsal point on the  
acromioclavicular joint  
Flex: Flexion, Abd: Abduction, EleScaPlane : Elevation in the Scapular Plane, HBB: Hand Behind  
Back, Ext Rot: External Rotation, Int Rot: Internal Rotation, HtM: Hand to Mouth, HtN: Hand to  
Neck, GH Abd: GlenoHumeral Abduction, GH Horiz Add: GlenoHumeral Horizontal Adduction.  
RMSE: Root Mean Square Error  
ANOVA: ANalysis of VAriance

1 **Table 5: Results of the reliability for the selected papers**

Study	Method of reference	Number of trials	Reliability coefficient	Within-Session	Between-Session
Lempereur et al. (2012)	Scapula Locator	3	CMC SEM	Excellent for the TH joint Good for the ST joint Good to excellent for the GH joint SEM inferior to 7°	
Shaheen et al. (2011)	Scapula Locator	3	Inter trial mean error	Inter-trial error inferior to 5.5° on average, much smaller than the calculated errors using the acromial tracker	
Brochard et al. (2011a)	Scapula Locator	3	ICC	Simple Calibration: good to excellent (0.75-0.96) Double Calibration: good to excellent (0.63-0.92)	SC: moderate to excellent (0.56-0.92) DC: moderate to good (0.49-0.78)
Brochard et al. (2011b)	Scapula Locator	3	ICC	Flex / Markers on AA, AI, TS : Y (0.94), X (0.93), Z (0.94) Abd / Markers on AA, AI, TS: Y (0.90), X (0.93), Z (0.92) Flex / AMC: Y (0.93), X (0.94), Z (0.94) Abd / AMC: Y (0.93), X (0.94), Z (0.91) Flex / anatomical AMC: Y (0.90), X (0.89), Z (0.91) Abd / anatomical AMC: Y (0.94), X (0.92), Z (0.91)	
Bourne et al. (2011)	Palpation AA, TS and AI	10 Day1 and Day2	ICC RMS		2.6°<RMS<8.1°
Jaspers et al. (2011a)	--	6	ICC SEM CMC	Moderately high to very high (ICC>0.6) SEM < 5°	ICC > 0.6 SEM < 7°
Jaspers et al. (2011b)	--	6	ICC SEM CMC	ICC > 0.7 SEM < 5°	ICC > 0.6 SEM < 5°
Lempereur et al. (2010)	Palpation AA, TS and AI	10	ICC	Good to excellent reliability 0.88 to 0.98	
Van Andel et al. (2009)	Scapula Locator	Day 1 and Day2	ICC SEM	Acceptable to good for protraction and external rotation. ICC low for tilt. Maximal SEM of 8.4°.	
Meskers et al. (2007)	Scapula Locator		RMSE	2.33°	5.0°
Hebert et al. (2000)	Palpation	2 Day1 and Day2	Coefficient of variation		< 10% for most of flexion and abduction task

2 CMC: coefficient of multiple correlations, SEM: Standard Error of Measurement, ICC: Intraclass  
3 Correlation Coefficient, RMSE: Root Mean Square Error

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5 AMC: Acromion Marker Cluster

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7 AA: Angulus Acromialis, AI: Angulus Inferior, TS: Trigonum Spinae

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9 Flex: Flexion, Abd: Abduction

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1 **Table 6: Methodological quality of the selected papers**

Study	Q 1	Q 2	Q 3	Q 4	Q 5	Q 6	Q 7	Q 8	Q 9	Q1 0	Q1 1	Q1 2	Q1 3	Q1 4	Q1 5	Q1 6	Q1 7	Q1 8	Total (Max=3 6)
Chu et al. (2012)	2	2	2	2	0	2	2	2	2	2	2	0	2	1	0	2	1	2	28
Warner et al. (2012)	2	2	2	2	0	2	2	2	2	2	2	0	2	2	0	2	2	2	30
Mattson et al. (2012)	2	0	2	2	0	1	2	2	2	1	2	0	2	1	0	2	2	2	25
Lempere ur et al. (2012)	2	2	2	2	0	2	2	1	2	2	2	2	2	2	0	2	0	2	29
Shaheen et al. (2011)	2	2	2	2	0	1	0	2	2	2	2	0	2	2	0	2	2	0	25
Prinold et al. (2011)	2	2	2	2	0	1	2	1	2	2	2	0	2	1	0	2	0	2	25
Brochard et al. (2011a)	2	2	2	2	0	2	2	2	2	2	2	2	2	1	2	1	1	2	31
Brochard et al. (2011b)	0	2	2	2	0	2	2	2	2	2	2	0	2	2	0	2	0	0	24
Bourne et al. (2011)	2	2	2	2	0	2	2	2	2	2	2	2	2	2	2	2	1	2	33
Jaspers et al. (2011a)	2	2	2	2	0	1	2	1	2	0	0	2	0	0	2	2	2	2	24
Jaspers et al. (2011b)	2	2	2	2	0	1	2	1	2	0	0	2	0	0	2	2	2	2	24
Senk & Chèze (2010)	2	2	2	2	0	1	2	2	2	2	2	0	0	2	0	2	1	2	26
Lempere ur et al. (2010)	2	2	2	2	0	2	2	2	2	1	0	0	2	1	1	1	2	2	26
van Andel et al. (2009)	2	2	2	2	0	0	2	2	2	2	0	2	2	2	2	2	2	2	30
Lovern et al. (2009)	2	2	2	2	0	0	2	2	2	2	0	0	0	2	0	2	1	2	23
Bourne et al. (2009)	2	2	2	2	0	0	2	2	2	2	2	0	0	2	0	2	2	2	26
Meskers et al. (2007)	2	1	2	2	0	0	2	2	2	2	1	2	2	2	1	2	1	1	27
Karduna et al. (2001)	1	2	2	2	0	0	2	2	2	2	2	0	0	2	0	2	2	1	24
Hébert et al. (2000)	2	2	2	2	0	1	2	2	2	0	2	2	2	2	2	2	1	2	30

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